







Failures in large-scale computing system

The number of components grows

- More and more transistors used
- But also more racks, cabinets, cables, power supplies, etc.
- Everything at a nearly constant reliability per part

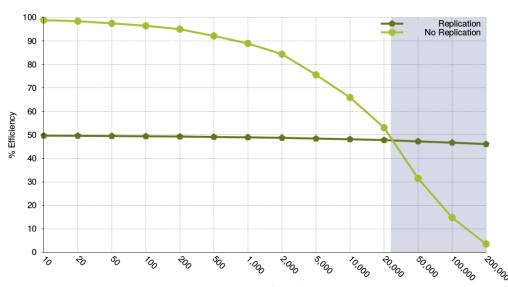
Things will fail!

- Wang et al., 2010: "Peta-scale systems: MTBF 1.25 hours"
- Brightwell et al., 2011: "Next generation systems must be designed to handle failures without interrupting the workloads on the system or crippling the efficiency of the resource."
 - Checkpoint/restart will take longer MTBF!

We need to enable applications to survive failures

- ... to reach Petascale Exascale!
- Like they did for decades in distributed systems!





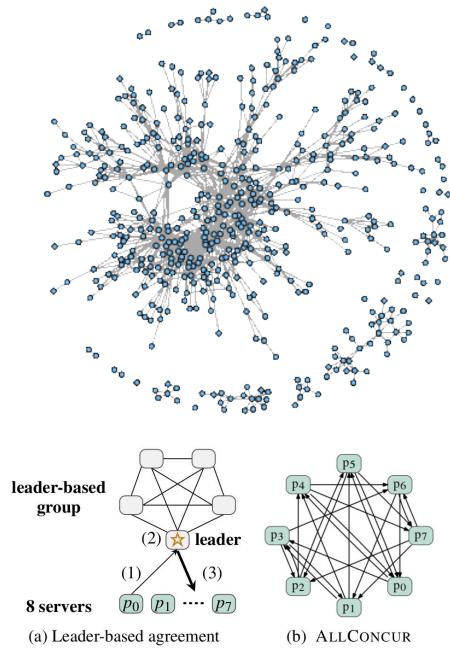






Distributed systems scenarios

- Loosely consistent systems based on gossip
 - Not all nodes always up to date
 - Sometimes eventual consistency
 - Weak ordering guarantees
 - Hard to control in general but may work well (e.g., load balancing)
- Strongly consistent systems based on atomic broadcast/consensus
 - Ordering guaranteed
 - Can survive up to k node failures, latency of k
 - Very limited in scalability
 Check our work on AllConcur at HPDC'17 though!
 - Usually low performance (limited to management tasks)
- High-performance systems are specialized
 - FARM Fast Remote Memory (consistent FT database)
 - Corrected Gossip for group communications (this paper)







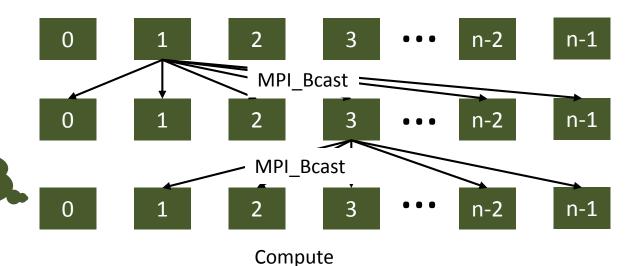


Specialized to HPC? Let's start with the simplest operation - broadcast

Gossip?

- If root or message received: send to random other node until some global time expires
- Proven to be very effective
- Not strongly consistent 🗵
- Nice theory needs 1.64 log₂ n rounds to reach all w.h.p.
- But for N=1000
 17 rounds only color all nodes 95% of the time

Where's my bcast?



Very problematic for BSP-style applications

 1
 2
 3
 ••• n-2
 n-1

 MPI_Reduce

 with rank 0?
 1
 2
 3
 ••• n-2
 n-1

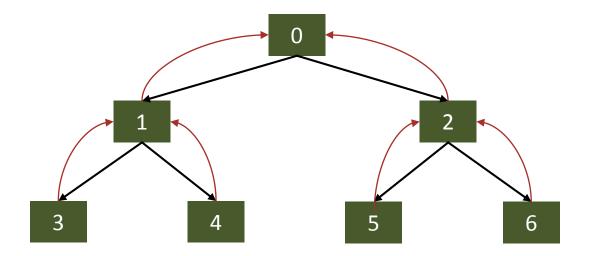






But how does FT-MPICH do this? Buntinas' FT broadcast

- Uses a dynamic tree, each message contains information about children at next levels
- Children propagate back to root, relying on local failure-detectors



- Complex tree rebuild protocol
- Root failure results in bcast never delivered
- At least 2 log₂ n depth!

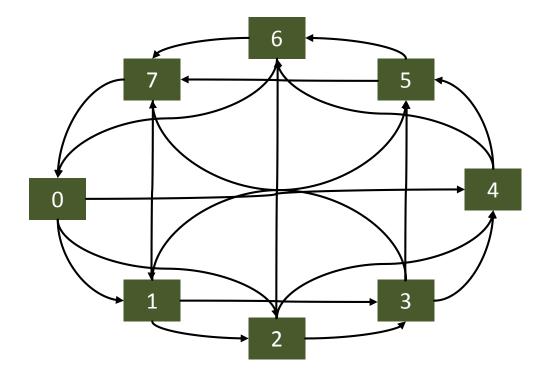






But how does FT-OpenMPI do this? Binomial graph broadcast

- Use fixed graph, send along redundant edges
- Binomial graphs: each node sends to and receives from log₂ n neighbors



- Can survive up to log₂ n worst-case node failures
 - In practice much more (not worst-case)







How to beat these algorithms?

- The power of randomness: gossip but <u>not just</u> gossip!
- Combine the probabilistic gossip protocol with a deterministic correction protocol



Corrected gossip turns Monte Carlo style gossiping algorithms into Las Vegas style deterministic algorithms!

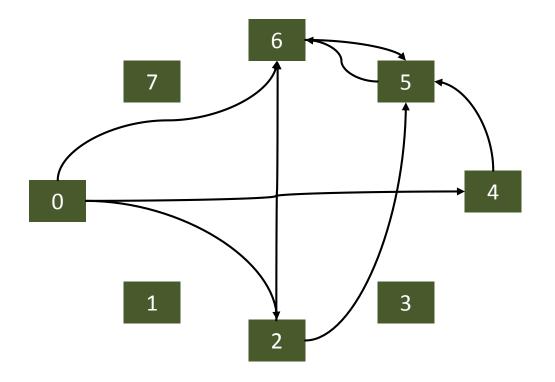
- But what is a fault-tolerant broadcast? Root failures, arbitrary failures?
 - Assuming fail-stop, four criteria need to be fulfilled:
 - 1. Integrity (all received messages have been sent)
 - 2. No duplicates (each sent message is received only once)
 - 3. Nonfaulty liveness (messages from a live node are received by all live nodes)
 - 4. Faulty liveness (messages sent from a failed node are either received by all or none live nodes)
- We relax 3+4 a bit: three levels of consistency
 - 1. Not consistent (we provide an improvement over normal gossiping)
 - 2. Nearly consistent (assuming no nodes fail during the correction phase, practical assumption)
 - 3. Fully consistent (any failures allowed)







Not consistent, works w.h.p. --- let's first consider just gossiping

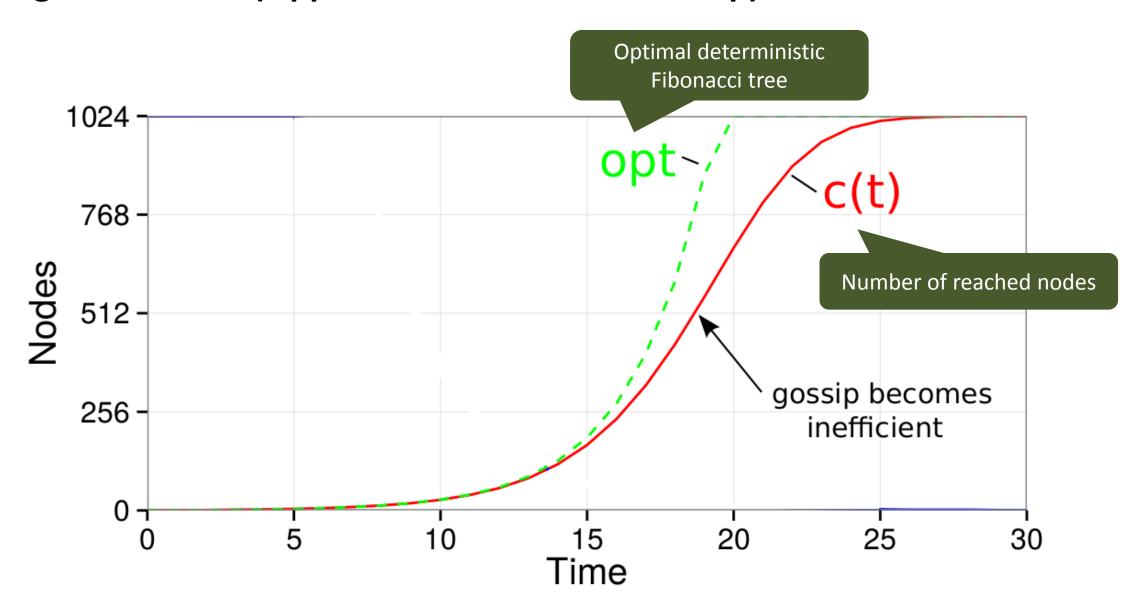


Are all these redundant messages efficient?







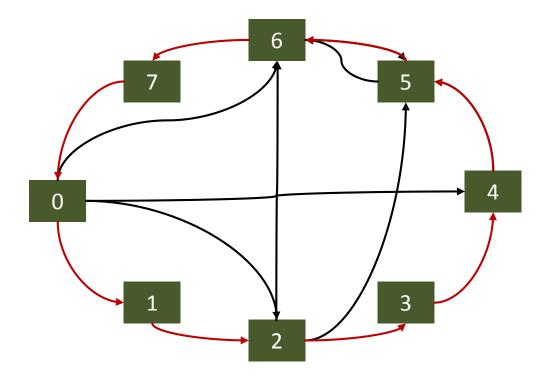








- OCG main idea: run gossip for a while and then switch to a ring-correction protocol
 - Every node that received a message sends it to (rank + 1) % nranks

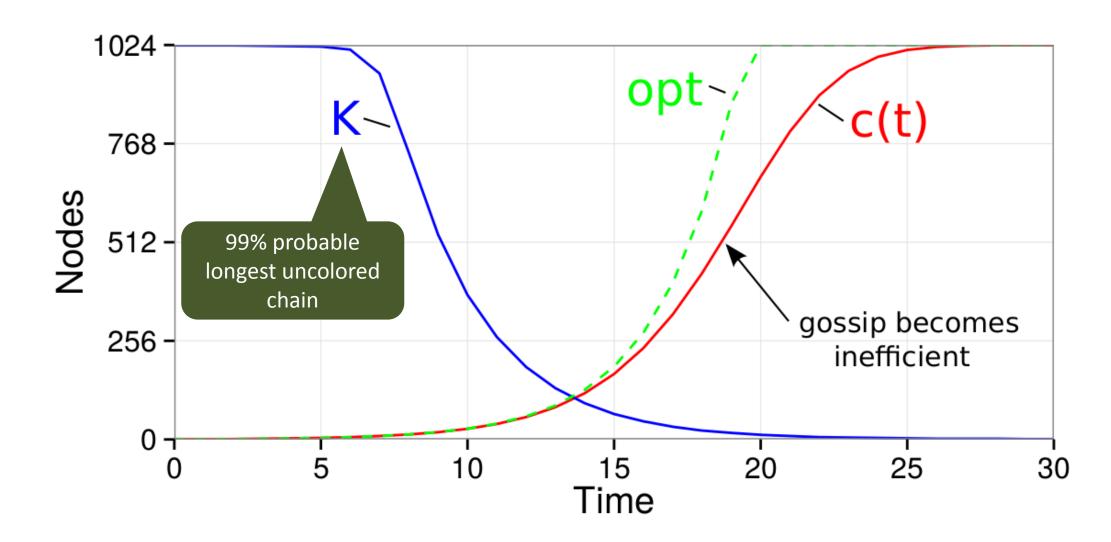


- Each message may be received twice
 - But this depends on when we switch! But what is the longest uncolored chain?





The longest uncolored chain!



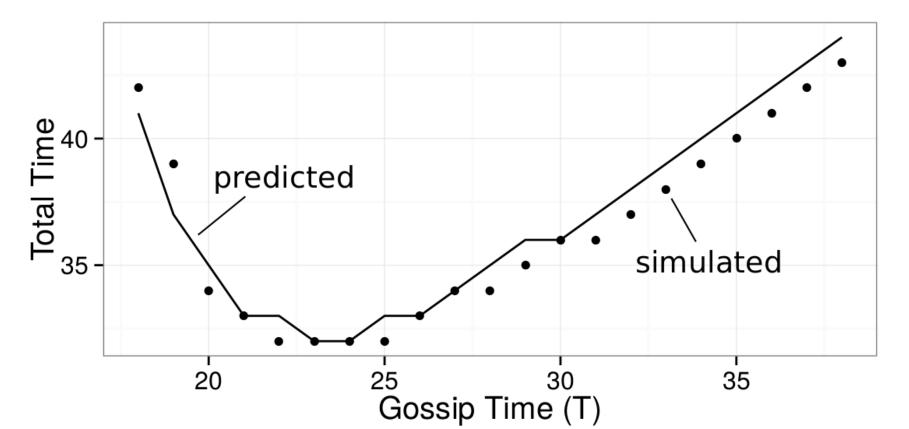


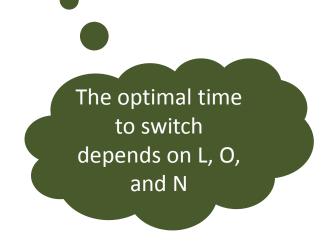




- When to switch from gossip to correction?
 - Well, when the expected number of correction steps is small and gossip is inefficient
- We can bound the probability of a longest chain of length k
 - In terms of the LogP parameters, T (gossip time), and N (nranks)

$$T_{opt}^{OCG} = \underset{T}{\operatorname{argmin}}(T + 2L + (2 + \overline{K})O)$$





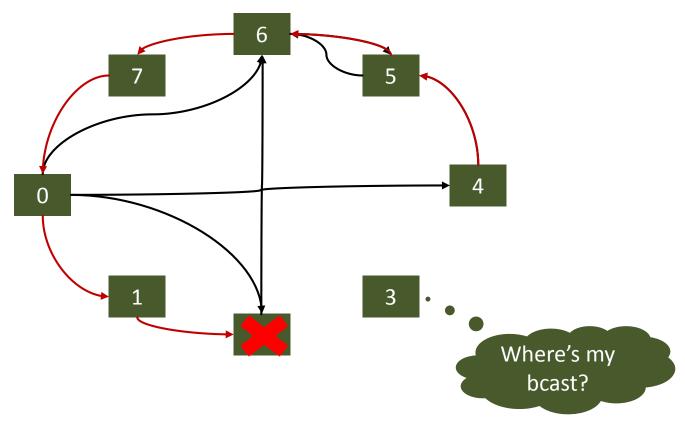






OCG Consistency

OCG is more efficient than gossip but does not guarantee that all nodes are reached (even w/o failures)



So we need to check that they were actually reached!

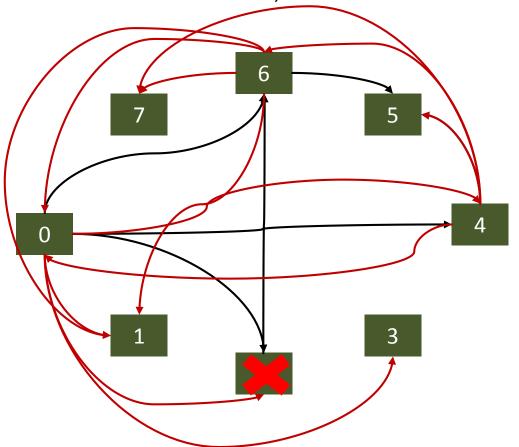






Second algorithm: CCG (Checked Corrected Gossip)

- CCG sends to the next node until it sent to a node it received from (i.e., knows that node was alive!)
 - Since the node it received from also sent, it "knows" that all other nodes have been covered!



- CCG guarantees that all nodes are reached unless a node dies in the middle of the correction phase!
 - And another node assumes it finished its job!

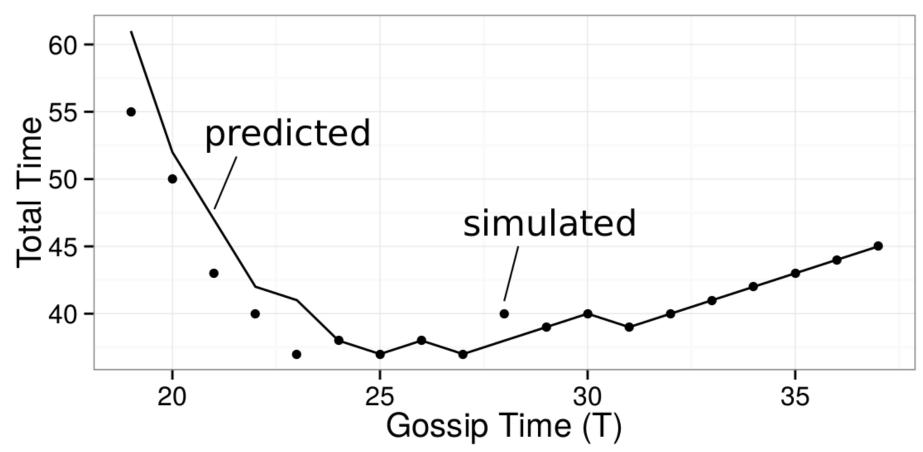






Second algorithm: CCG (Checked Corrected Gossip)

When to switch from gossip to correction?



A bit later than OCG







Third algorithm: FCG (Failure-proof Corrected Gossip)

- FCG can protect from f failures similar to CCG but instead of aborting to send when heard from one, it waits to hear from f+1 other nodes!
- So any f nodes can fail and it will still succeed (keep sending)
- Wait, what if there are less than f+1 nodes reached during gossip and they somehow die in the middle of the protocol?
 - So we need to involve the non-gossip-colored nodes
 - They will wait to hear from a gossip-colored nodes to exit
 - If no such exit signal comes within a timeout period, panic!
 - In panic mode, send to every other node
 - Every node that receives panic messages also panics
 - This guarantees consistency (at a high cost)
- Panic mode is extremely unlikely in practice (much less likely than the failing of binomial graphs)
 - Likelihood can be reduced arbitrarily with gossiping time!
 - So panic is just a theoretical concern (to proof correctness)







Observations and Optimizations

Why the ring topology?

- One could choose different topologies (e.g., broadcast trees), we did not find a better practical one
- This seems to be an interesting research topic

Optimization: bidirectional

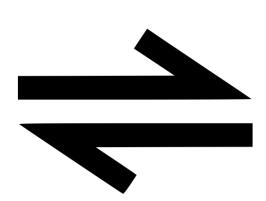
- In fact, all our algorithms send backwards and forward along the ring
 We skipped it to simplify the explanation
- Buys a factor of two, very practical (very impactful for CCG/FCG)

Does the principle generalize

We believe so, more algorithms to come!

Both the binomial graphs and FCG require to pick an f, is there a total consistency?

- Only if f=N-2, which is not practical
- Yet, both algorithms can be configured for an arbitrarily high success probability!









Case study: TSUBAME 2.0

Gossip

- TiTech machine, published failure logs
- MTBF = 18304 hours
 - Assume 12 hour run on 4096 nodes = 2.69 failures
- We compare all algorithms and report
 - 1. Expected latency
 - 2. Expected work
 - 3. Expected inconsistency For CCG/OCG/FCG, we simulate until the nonparameric CI was within 2% of the median

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Binomial Graphs

Buntinas' Tree

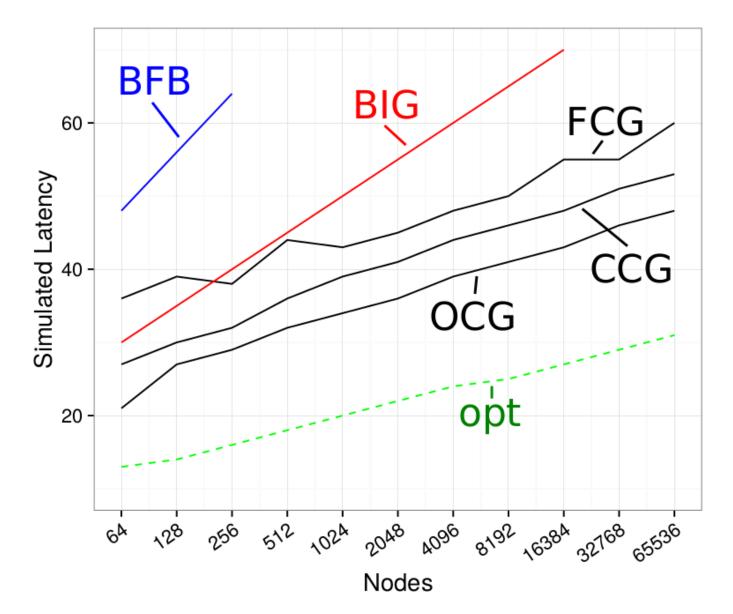
algorithm	$ \hat{f} $	T	lat	work	incon.
GOS [12]	0				
GOS [12]	3				
OCG	0	_	Ī	Ī	
OCG	3				
CCG	0	_	Ī	Ī	
CCG	3				
FCG	0		Ī	Ī	
FCG	3				
BIG [2]	0		Ī	Ī	
BIG [2]	3				
BFB [8]	0	_	Ī	Ī	
BFB [8]	3				



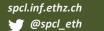




Scaling – Without failures

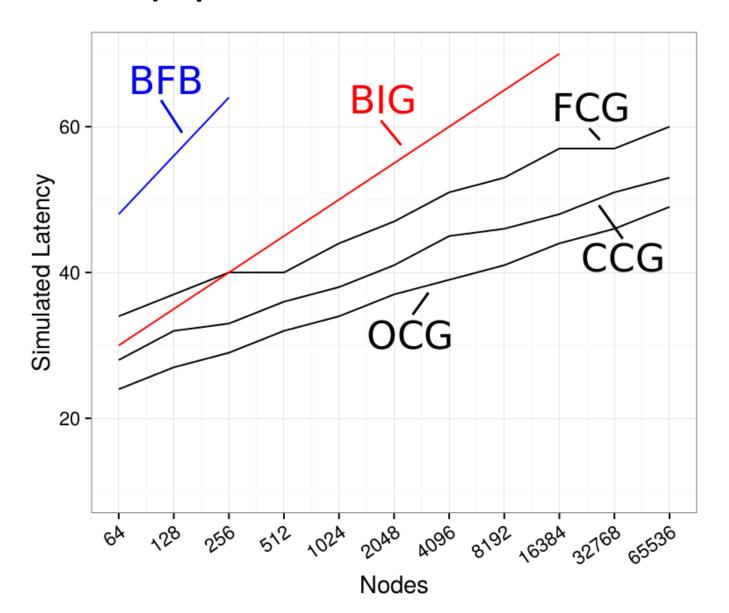








Scaling – With failures (expected for 12 hours on TSUBAME 2.0)



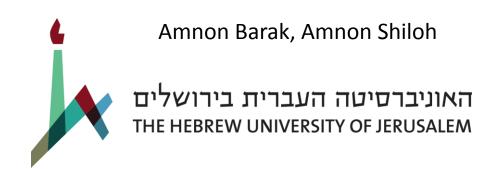






Summary and Conclusions

- New principle to implement fault-tolerant group communications
 - Combines randomness and determinism Las Vegas style algorithms
- Three versions with growing consistency
 - Opportunistic Corrected Gossip
 - Checked Corrected Gossip
 - Failure-proof Corrected Gossip
- Analytic models to selecting parameters
 - Fast to compute gossiping time
- Now we need to see if it's practical
 - May need some hardware support In a trivial implementation, wasted o dominate!



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